

A.C.N. 009 183 082

LOGISTICS REPORT

ARTHUR - PIEMAN AREA NORTH WEST TASMANIA

for

TASMANIA DEVELOPMENT AND RESOURCES

by

TESLA AIRBORNE GEOSCIENCE PTY LTD

<u>June 1996</u>

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INTRODUCTION

On the 22nd March 1996 Tesla Airborne Geoscience Pty Ltd was contracted to acquire and process airborne geophysical data for Tasmania Development and Resources.

All final processing and map production was carried out by Tesla-10 Pty Ltd in their Kariong office in New South Wales.

1. SURVEY DETAILS

The North West Tasmania airborne survey covers sections of the 1:100,000 Tasmania World Aeronautical Chart.

a) SURVEY LOCATION

A map of the survey area location can be found in Appendix A. The co-ordinates of the boundary lines, beginning at the north west corner and preceding clockwise, are as follows:

300719.000E	5460000.000N
335000.000E	5460000.000N
335000.000E	5442000.000N
337500.000E	5442000.000N
341500.000E	5438500.000N
341500.000E	5411000.000N
352500.000E	5405000.000N
352500.000E	5379000.000N
333000.000E	5379000.000N
333000.000E	5378481.000N
327379.000E	5378481.000N
325753.000E	5382638.000N
326536.000E	5383604.000N
326468.000E	5384672.000N
324773.000E	5388002.000N
325225.000E	5389395.000N
321983.000E	5396663.000N
315638.000E	5407374.000N
315184.000E	5408964.000N
311615.000E	5411872.000N
310437.000E	5423377.000N
308985.000E	5425283.000N
305738.000E	5432298.000N
306301.000E	5436537.000N
304462.000E	5440557.000N
303904.000E	5445113.000N

304791.000E 5447183.000N 303367.000E 5451605.000N 301195.000E 5454000.000N 298500.000E 5457000.000N

The area traversed Australian map grid zone 55. The traverse and tie lines were flown along AMG Eastings and Northings.

The aircraft and crew were based at Smithton in Tasmania for the duration of the survey.

b) SURVEY SPECIFICATIONS

Survey	Distance	Flown
SULLI V C Y	DIDIVITION	T POILE

Traverse Lines	:	15,564.8	kilometres
Tie Lines		1,529.8	kilometres
TOTAL		17,093.8	kilometres

ran .	α·		000
Traverse	macina	•	200 metres
IIIAVUISU	DUACINE	4	200 11101108

Traverse Direction : AMG Grid East/West

Tie Spacing : 2,000 metres

Tie Direction : AMG Grid North/South

Flying Height : 90 metres

Sample Intervals

Magnetics : 0.1 second (6-8 metres)
Gamma-Ray Spectrometer : 1.0 second (60-80 metres)
GPS : 1.0 second (60-80 metres)
Radar Altimeter : 0.1 second (6-8 metres)
Barometric Pressure : 1.0 second (60-80 metres)
Temperature/Humidity : 1.0 second (60-80 metres)

A summary of the survey progress can be found in the Operations Report - Appendix B.

2. PERSONNEL

Pilots : T. Anderson (Crew Leader)

R. Wright

Operators : B. Anderson

M. Ostich

Electronics Technician : P. McMullen

T. Grzelak

Data Processing : B. Merritt

L. Nix

Project Supervision : R.Pullin

3. AIRCRAFT AND EQUIPMENT

a) SUMMARY

Aircraft

Model :

Cessna 210N

Registration

VH-BNZ

Compensator

Model

RMS Instruments Automatic Aeromagnetic Digital

Compensator

Magnetometer Sensor

Model

Scintrex CS-2

Mounting

Tail Stinger

Sample Interval

0.1 seconds (6-8 metres)

Sensitivity

 $0.001 \, nT$

Vector Magnetometer

Model

Billingsley TFM100-IE (3-axis fluxgate)

Gamma-Ray Spectrometer

Model

Exploranium GR820 Self Calibrating Spectrometer

Detectors : 8 All Viewin

8 All Viewing NaI (Tl activated) Crystals Total Crystal Volume - 33.6 Litres

Sample Interval :

1.0 seconds

Number of Channels:

4 ROIs (TC, K, U, Th), Cosmic and 256 Channels

Computer

Model

486 DX2/66

Acquisition Software

Programme

Custom in-house developed TAG3 acquisition

software

Version

3

Aircraft Navigation

GPS, Model :

Novatel 951R

Update rate :

0.5 seconds

Radar Altimeter

Model :

Bendix King KRA 10A

Sample Interval :

0.1 seconds

Temperature/Humidity

Model :

Vaisala HMD 50Y

Sample Interval

1.0 seconds

Pressure

Model

Intellisensor AIR-DB

Sample Interval

1.0 seconds

Base Station Magnetometers

Model

.

Geometrics G-856

Sample Interval

6.0 seconds

Base GPS

Model

.

Novatel 951R

Sample Interval

1.0 seconds

b) MAGNETOMETER AND COMPENSATOR

A Scintrex CS-2 Magnetometer Sensor, mounted in a stinger secured to the rear of the aircraft was used for this survey. The specifications of the Magnetometer Sensor are summarised in Appendix G.

The Magnetometer Sensor was coupled to a RMS Instruments Automatic Aeromagnetic Digital Compensator (AADC). The AADC compensates the total magnetic field data in real time for the magnetic interference caused by the aircraft manoeuvring in the earth's magnetic field and by the aircraft itself.

The correction coefficients used by the AADC during compensation, were calculated from a compensation flight conducted prior to the survey commencing, or at any other time deemed necessary.

The specifications of the AADC are summarised in Appendix H.

Compensation procedures are described in Section 4.

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An Exploranium GR-820 Multi-channel Gamma-Ray Spectrometer, coupled to two GPX-1024 Crystal Detectors with a total volume of 33.6 litres were used for this survey. The Crystal Detectors were mounted in two packs, side by side secured to a rack on the floor of the aircraft.

The specifications of the Gamma-Ray Spectrometer are summarised in Appendix I.

The GR-820 uses a sophisticated automatic control method to ensure crystal alignment is maintained, while stabilising on naturally occurring isotopes. The system continuously monitors each of the eight crystal signals and accumulates an individual spectra for each configured signal. The peak channel of the selected stabilisation isotope is computed when a specified number of counts have been accumulated. This peak channel is then compared to the correct peak location and the gain is subsequently adjusted.

Two hundred and fifty six channels of data between 0.3 MeV and 3.0 MeV were recorded once per second. Additionally, 4 ROIs and a cosmic channel were recorded using the following window limits:

Total Count	:	0.41 - 2.81 MeV
Potassium (K40 peak at 1.46 MeV)	•	1.37 - 1.57 MeV
Uranium (Bi214 peak at 1.76 MeV)	:	1.66 - 1.86 MeV
Thorium (T1208 peak at 2.61 MeV)	•	2.41 - 2.81 MeV
Cosmic	:	3.00 - 6.00 MeV

The calibration procedures for the Gamma-Ray Spectrometer system are described in Section 4.

d) DATA ACQUISITION SYSTEM

The TAG3 Acquisition System runs on a 486 personal computer. The data was recorded to hard disk and dumped to DC2120 data cartridge at the completion of each flight. The system was synchronised to GPS time. The data was viewed in real time, enabling the operator to confirm that quality specifications are being met. The following parameters were recorded digitally.

- (a) Time in seconds (to 0.1 seconds)
- (b) Fiducial number, incrementing by smallest data sample interval
- (c) Navigation data including GPS height
- (d) Terrain clearance (radar altimeter)
- (e) Barometric pressure
- (f) Relative humidity
- (g) Ambient temperature outside the aircraft in degrees Celsius
- (h) Uncompensated Magnetometer reading
- (i) Fluxgate x, y, z
- (j) Fluxgate Total Field
- (k) Raw Magnetometer 4th Difference
- (1) Compensated Magnetometer reading
- (m) Full 256-channel gamma-ray spectrum
- (n) Total count reading in counts per second (uncorrected)
- (o) Potassium window reading in counts per second (uncorrected)
- (p) Uranium window reading in counts per second (uncorrected)
- (q) Thorium window reading in counts per second (uncorrected)
- (r) Cosmic window reading in counts per second (uncorrected)

e) NAVIGATION

The GPS position, referencing WGS84, is read by the TAG3 acquisition system. This is the first step in the TAG3 navigation cycle. The position is then transformed to the AGD84 datum using the full 7 parameters. Conversion to AMG co-ordinates follows. The navigational errors, with reference to the planned survey line, are then calculated and displayed for the pilot and operator. This completes the cycle. Two navigation cycles are performed each second.

Real time differential correction was achieved via Fugro Surveys Omni Star System.

The Novatel 951R Global Positioning System card specifications can be found in Appendix J.

f) RADAR ALTIMETER

A Bendix King KRA-10A Radar Altimeter was used to measure the aircraft height above ground level (AGL). The Radar Altimeter System is of high resolution designed for automatic continuous operation over a wide variation of terrain, target reflectivity, weather and aircraft altitude.

The Radar Altimeter data was recorded 10 times per second with an accuracy of \pm 1 m (at 80 m AGL).

Bendix King KRA-10A Radar Altimeter specifications can be found in Appendix K.

g) TEMPERATURE AND HUMIDITY

A Vaisala HMD50Y Sensor was used to measure outside air temperature and relative humidity. The data was recorded once per second.

Vaisala HMD50Y Sensor specifications can be found in Appendix L.

h) BAROMETER

Atmospheric pressure was measured using a Intellisensor Air-DB Digital Barometer that was tapped into the aircraft static system. The barometric data was recorded once per second.

Intellisensor Air-DB Digital Barometer specifications can be found in Appendix M.

i) BASE STATION MAGNETOMETER

Diurnal variations in the earth's magnetic field were recorded using two Geometrics G856 Proton Precession Base Station Magnetometers. The Base Stations were located away from cultural influences in an area of shallow magnetic gradient. They were cycling at a 5 second sample interval at all times the aircraft was on survey.

At the completion of each days flying, the data was dumped onto an infield processing computer, where data quality and compliance with contractual specifications were checked. The data was subsequently backed up onto a data cartridge tape for shipment to the processing office.

Base Station Magnetometer specifications can be found in Appendix N. Base Station Magnetometer records can be found in Appendix E.

j) GPS BASE STATION POSITION

Final in-field aircraft positional information was determined post flight.

An accurate GPS Base Station position was calculated by recording latitude, longitude and height information over a seven to twelve hour period and then averaging these positions.

The final GPS Base Station position was then entered into the "Ranger" software and used to calculate post flight differentially corrected aircraft positions. This procedure was conducted at the completion of each flight.

The differentially corrected flight path was then viewed to ensure it did not exceed contractual specifications.

GPS Base Station records can be found in Appendix F.

4. CALIBRATION

a) MAGNETIC COMPENSATION

The compensation sequences were flown in a region of low magnetic relief located approximately 10 km North West of Smithton. The aircraft's altitude was 8,000 feet (above mean sea level).

Each sequence consisted of a series of manoeuvres performed on each of the cardinal headings. The manoeuvres comprised \pm 10 degree rolls, \pm 5 degree pitches and \pm 5 degree yaws.

The coefficients used in compensating for the effects of permanent magnetism, induced magnetism, eddy currents and heading error were calculated automatically by the AADC upon completion of a sequence. The calculated coefficients were then applied to the uncompensated total field readings (collected during the sequence) in order to assess the quality of the "solution". This (now compensated) data was then statistically analysed. The resultant statistics, revealing the quality of the compensation solution, are displayed by the AADC.

A three-axis fluxgate magnetometer, mounted in the stinger, enables derivation of motion information by the AADC during a sequence.

The statistics include: standard deviation of the high-passed uncompensated (UNC), standard deviation of the high-passed compensated (CMP), improvement ratio (IR) and "vector norm of the interference set" (NRM). The IR is the result of dividing UNC by CMP.

b) GAMMA-RAY SPECTROMETER CALIBRATION

At the commencement and conclusion of each day's production, a low level test line was flown and ground calibrations performed. Statistics were calculated and recorded for each of the calibration processes.

i) The Low Level Test Line

The low level test line was located along a fence line orientated in a North/South direction, approximately 12 kilometres South East of Smithton. The test lines were flown at survey height. The start and end points were visually definable positions captured as GPS waypoints for ease of orientation and reference purposes.

The test line was always flown to the North and South.

ii) Ground Radiometric Button Checks

Crystal stabilisation using Thorium was undertaken prior to each day's acquisition. For each ground calibration, the aircraft was parked in exactly the same position. Similarly the spectrometer button samples were positioned in exactly the same location with reference to the detectors.

The precision involved in all calibrations ensured the statistics were an accurate indication of the Gamma-Ray Spectrometer system status.

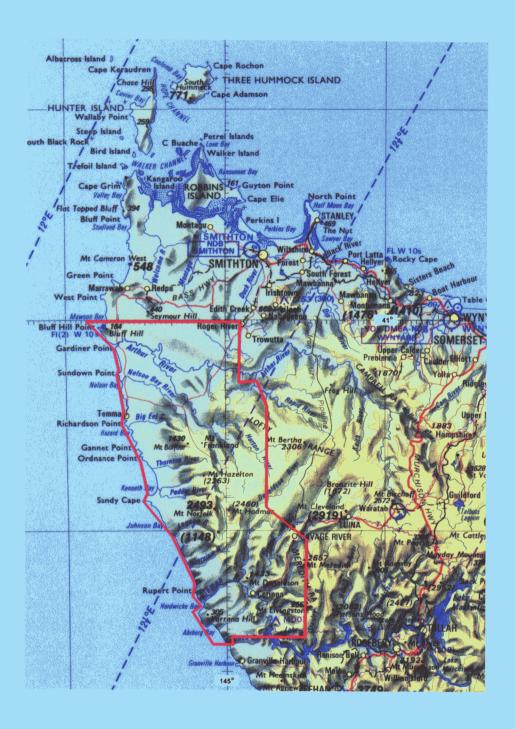
The statistics for both the low level test lines and ground radiometric button checks were recorded on a calibration log with appropriate figures transferred to various spreadsheets. These statistics were compared with those from preceding flights in order to detect any irregularities and to ensure contractual requirements were being met.

This was primarily achieved through calculating the percentage difference in statistics from the most recent calibration to statistics of the running average of all previous calibrations. Some variation was occasionally noticeable in the Total Count and Uranium windows, due to the effects of daily Radon variations.

Copies of the Calibration Spreadsheets can be found in Appendix D.

APPENDIX A Arthur - Pieman Area North West Tasmania

ARTHUR - PIEMAN AREA NORTH WEST TASMANIA



APPENDIX B <u>Arthur - Pieman Area</u> <u>North West Tasmania</u>

TESLA AIRBORNE GEOSCIENCE OPERATIONS REPORT TASMANIA DEVELOPMENT AND RESOURCES VH-BNZ JOB No. TA2294

	JUB NO. TAZZ94											
						ME ¦ LAND	THIS PROD	FLT REFL	TO PROD	DATE REFL	RUNNING	COMMENTS
1	02-Apr		TA	: !	 ! !	:: !		0.0				AIRCRAFT TRAVELS FROM DUBBO TO SMITHTON
JULIAI DAY	N 93 0			! ! !	! ! !	! ! ! ! !	0.0	0.0		0.0	0.0	
	03-Apr				1400		34.7			 		COMP BOX & TEST LINE
JULIA	N 94 1	: ! ! !	! ! !	! ! !	 		34.7	0.0	34.7	0.0		STAND-BY BAD WEATHER 1/2 DAY
THUR	04-Apr N 95				700		864.2 758.5	26.3		1 1 1 1 1	! ! !	
DAY	2	1	! ! !	!	1	; ;	1622.7	26.3	1657.4	26.3	828.7	
į	05-Apr	5	RW	MO	1225		638.5 619.1	26.3		1		COMP BOX
JULIA:	3					: : :	1257.6	26.3	2915.0	52.6	971.7	
1	06-Apr	i								;		STAND-BY BAD WEATHER
JULIA	N 97		1 1 1 1	i ! !	1 7 8 8	† 1 1 1	0.0	0.0	2915.0	52.6	728.8	
	07-Apr				725 1310		989.0 249.7			;		STAND -BY BAD WEATHÊR 1/2 DAY
JULIA	N 98	i !	1	1 1	i !		1238.7	0.0	4153.7	52.6	830.7	
	08-Apr				657 1215		662.6			 		STAND -BY BAD WEATHER 1/2 DAY
DAY	N 99		1 8 8	!	1	1	991.9	0.0	5145.6	52.6	857.6	
	09-Apr				710 1135		566.7 860.2	0.0				SHORT FLIGHT DUE TO GPS CARD PROBLEMS
JULIA	N 100 7	====	: ! ! ===	===	=====	: ! ! =====	1426.9	0.0	6572.5	0.0	6572.5	

WED 10-Apr	12	RW TA	MO BA	645	1150 1725	695.4	10.0				LINE 10045 COMPLETED - REFLY
DAY 8			1	i i _ ;		1422.5	10.0	7995.0	10.0	999.4	
THUR 11-Apr	14 15	TA RW	BA MO	655 1250	1155	701.8				; ; ; ;	
DAY 9			1	1 1 1		1290.9	0.0	9285.9	10.0	1031.8	
FRI 12-Apr	16	RW	MO	1456	1800	380.0					
JULIAN 103 DAY 10		!		i ! !	i ! !	380.0	0.0	9665.9	10.0	966.6	
SAT 13-Apr JULIAN 104 DAY 11					1530	894.7 325.9 -0.2 1220.4		10886.3	10.0	1	STAND-BY 1/2 DAY BAD WEATHER CORRECTION DUE TO ROUNDING ERRORS
SUN 14-Apr											
JULIAN 105 DAY 12	i t 1 1	; ; t ; ;	1	! ! ! ! !	; ; ; ;	0.0	0.0	10886.3	10.0	907.2	BNZ 100 HRLY
MON 15-Apr JULIAN 106				658		678.9 281.9				•	COMP BOX STAND -BY BAD WEATHER 1/2 DAY
DAY 13	f 1	1	1 1 1	1 1 1	1 1	960.8	0.0	11847.1	10.0	911.3	
TUE 16-Apr				645 1216		681.6 230.2	66.1				STAND-BY BAD WEATHER 1/2 DAY
DAY 14			i i		i 1 1	911.8	66.1	12759.0	76.1	911.4	

WED 17-Apr											STAND-BY BAD WEATHER
JULIAN 108 DAY 15	1 1 1 2 3	; ; ; ;	! ! !			0.0	0.0	12759.0	76.1	850.6	
THU 18-Apr				654 1230	1200 1725	802.2 658.6	140.0				1 1 1 1 1
JULIAN 109 DAY 16		i . I . I .		[1 f	1460.8	140.0	14219.8	216.1	888.7	
FRI 19-Apr	25	TA	МО	950	1415	620.2					STAND-BY BAD WEATHER 1/2 DAY
JULIAN 110 DAY 17	! ! !		; ; ; ;	; ; ; ; ;	; 	620.2	0.0	14840.0	216.1	872.9	
SAT 20-Apr	26	TA	МО	1510	1710	241.0					STAND-BY 1/2 DAY BAD WEATHER
JULIAN 111 DAY 18	1 1 1				1	241.0	0.0	15063.2	216.1	836.8	CORRECTION, DOUBLE COUNTING REFLY -17.797
SUN 21-Apr	27	TA	МО	655	745	0.0	6.0				REFLY PART OF 10030, INFILA COULD NOT BE FLOWN DUE TO BAD WEATHER STAND-BY DAY BAD WEATHER
JULIAN 112 DAY 19	i !	1	1	1		0.0	6.0	15063.2	222.1		
MON 22-Apr	28	RW	BA	710	1030	499.4	0.0				COMPLETION OF JOB
JULIAN 113 DAY 20	1 3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		1	: : : : :	: : : :	499.4	0.0	15562.6	222.1	778.1	
	,	1	,	1	,	1	1		1	1	I control of the cont

APPENDIX C

<u>Arthur - Pieman Area</u>

<u>North West Tasmania</u>

APPENDIX C

Specifications - Geometrics G-856 Magnetometer

DISPLAYS : Six digit display of magnetic field to resolution of 0.1 gamma or

time to nearest second. Additional three digit display of station,

day of year, and line number.

RESOLUTION : Typically 0.1 gamma in average conditions. May degrade to

lower resolution in weak fields, noisy conditions or high gradients.

ABSOLUTE ACCURACY : One gamma, limited by remnant magnetism in sensor and crystal

oscillator accuracy.

CLOCK : Julian clock with stability of five seconds per month at room

temperature and five seconds per day over the temperature range

of -20 to +50 degrees Celsius.

TUNING: Push button tuning from keyboard with current value displayed

on request. Tuning range 20 to 90 kilogammas.

GRADIENT TOLERANCE : Tolerates gradients to 5000 gammas/meter. When high gradients

truncate count internal, maintains partial reading to an accuracy

consistent with data.

CYCLE TIME : Complete field measurement in three second in normal operation.

Internal switch selection for faster cycle (1.5 seconds) at reduced

resolution or longer cycles for increased resolution.

MANUAL READ : Takes reading on command. Will store data in memory on

command.

MEMORY : Stores more than 1000 readings in survey mode, keeping track of

time, station number, line number, day and magnetic field reading. In base station operation, computes for retrieval but does not store time of recording designated by sample interval,

allowing storage of over 2500 readings.

OUTPUT : Plays data out in standard RS-232 format at selectable baud

rates. Also outputs data in real time byte parallel, character serial

BCD for use with digital recorders.

INPUTS : Will accept an external sample command.

SPECIAL FUNCTIONS

An internal switch allows:

1) adjustment of polarisation time and count time to improve performance in marginal areas or to improve resolution or speed operation,

2) three count averaging,

3) choice of lighted displays in auto mode.

PHYSICAL

Instrument console: 18 x 27 x 9 cm (2.7 kg)

Sensor: 9 x 13 cm (1.8 kg)

Staff Section: 3 cm x 60.5 cm (0.4 kg)

ENVIRONMENTAL

Meets specifications from 1 to 40 °C Operates satisfactorily from -20 to 50 °C

Weatherproof.

POWER

Operates from 8 D-cell flashlight batteries (or 12V external power). May be operated at 18V external power to improve resolution. Power failure or replacement of batteries will not cause loss of data stored in memory.

APPENDIX D

<u>Arthur - Pieman Area</u>

North West Tasmania

APPENDIX E

<u>Arthur - Pieman Area</u>

<u>North West Tasmania</u>

TESLA AIRBORNE GEOSCIENCE THORIUM BUTTON CHECKS TASMANIA DEVELOPMENT & RESOURCES VH-BNZ JOB No - TA2294

TESLA AIRBORNE GEOSCIENCE TESTLINE RADIOMETRIC DATA TASMANIA DEVELOPMENT & RESOURCES VH-BNZ JOB No - TA2294

TACMANIA	DEVELOPMENT	AND	RESOURCES
			MUDUUMULD

APPENDIX F

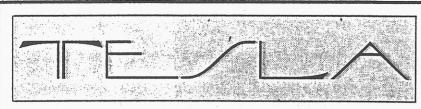
<u>Arthur - Pieman Area</u>

<u>North West Tasmania</u>

CLIENT NAME

APPENDIX E

<u>Survey Area</u>



AIRBORNE GEOSCIENCE

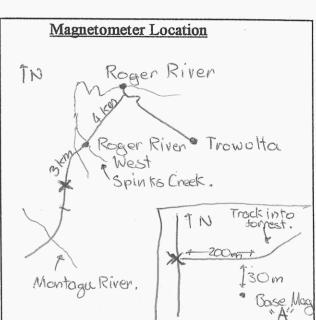
VH-RX12

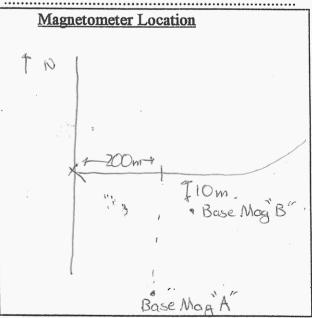
Completed by: BART

A.C.N. 009 183 082

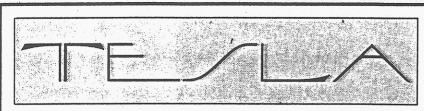
BASE MAGNETOMETER RECORD

	Job No: Client:	TAZZOI, TASMANIA DEVELOPMENT & RESOURCES	Aircraft: Date:
	Area: Crew Leader: Operator:	NORTH WEST TASMANIA TIM BART	Julian: Completed Signature:
	Magnetometer	Type: <u>6-856</u>	Mag
	Serial No.	50663	TN
	Magnetometer	Location RUGER RIVER WEST	
BASE	Cycle Rate:	1 READING EVERY S SECONDS.	m the
"A"	Sensor Height Readings: 2m North 2m South 2m East 2m West Central	616862 61687.9 61685.1 61687.5	Monto
	Magnetomete	r Type: 6-886	Mag
	Serial No.	27 881	10
	Magnetomete	r Location ROGER RIVER WEST.	
	Cycle Rate:	1 READING EVERY S SECONDS	
BASE MAG "B"	Sensor Height Readings: 2m North 2m South 2m East 2m West Central	61658.0 61659.6 61659.6 61659.8 61659.9	





Ref: ADM1479



AIRBORNE GEOSCIENCE

A.C.N. 009 183 082

BASE MAGNETOMETER RECORD

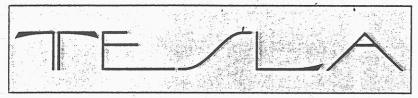
J00 No:	TA2294	Aircraft: VH僧-5N之,
Client:	TASMANIA DEVELOPMENT ARESOURCES	Date: $03/04/96 - 08/04/96$.
Area:	NORH WEST TASMANIA	Julian: 694/099.
Crew Leader:	TIM	Completed by: BART
Operator:	BART	Signature:
Magnetometer	Type: ENVI.	Magnetometer Location TN
Serial No.	9403068.	Hauger Terminal
Magnetometer	Location SMITHTON AIRPORT.	Hansey
		1 tongers
		ENVI
Cycle Rate:	1 READING EVERY C SECONDS	MAG
	3 POLES.	
Readings:		
	61811.0	
	61810.7	
2m East	61809.3	//
2m West _ Central	61810.9.	25/4/
	01810-3	
Magnetomete	т Туре:	Magnetometer Location
0 1137		
Serial No.		
Magnetomete		
Magneromere	r I continu	
	r Location	
	r Location	- 1
	r Location	
Cycle Rate:	r Location	-
Cycle Rate:		
Cycle Rate: Sensor Height		
Cycle Rate: Sensor Height Readings: 2m North 2m South		
Cycle Rate: Sensor Height Readings: 2m North 2m South 2m East		
Cycle Rate: Sensor Height Readings: 2m North 2m South		

PLEASE NOTE: BASE MAGA, WAS IN ENVI MAG'S Ref: ADM1479
POSITION UNTILL THE 08/04/96. FROM THEN ON
IT WAS IN ITS RECORDED POSITION. BASE MAG B NEVER MOVED.
41 Kishorn Road, Applecross, Western Australia 6153

41 Kishorn Road, Applecross, Western Australia 6153 Telephone (09) 364 8444 Fax (09) 364 6575 **CLIENT NAME**

APPENDIX F Survey Area

Ref:ADM1480



AIRBORNE GEOSCIENCE

A.C.N. 009 183 082

BASE GPS RECORD

JobNo. Client: Area: Aircraft: Crew Leader: Operator:	TAZZ94 TASMANIA DEVELO NORTH WEST TO VH-RNZ TIM BART	S C	erial No: completed By: ignature:	03/04/96 094 94/00021-V322. BART
Calculated Base S Co-ordinates Ellipsoid		D-8391520	Long 148 Height 13	5.119.3345 -86143
Method of Position	on Determination		ra in Samula 16	1876 (<=16 12 379)
		Sample Interval		SECONDS
		Standard Deviation	of Sample _2	3-78.
		Other		
Differential Corre	ection Method:	FDG-RTCA		
Location of GPS Comments	Antenna/	BRIDGE HO	TEL MOTE ENNA PO ROT NEA	

APPENDIX G

<u>Arthur - Pieman Area</u>

<u>North West Tasmania</u>

APPENDIX G

Specifications - Scintrex CS-2 Cesium Magnetometer Sensor

OPERATING PRINCIPLE

Self-oscillating Cesium Vapour Magnetometer

MEASUREMENT RANGE

15000 nT to 100000 nT

GRADIENT TOLERANCE

40000 nT/meter

TEMPERATURE LIMITATIONS:

-40°C to 50°C

SUPPLY VOLTAGE

27 to 35V DC

OUTPUT

Continuous signals at the Larmor frequency which is

proportional to the magnetic field (proportionally constant

3.498577 Hz/nT)

POWER CONSUMPTION

15W at 20°C

DIMENSIONS

Diameter - 63 mm

Length - 160 mm

WEIGHT

 $1.15 \, \mathrm{kg}$

APPENDIX H Arthur - Pieman Area North West Tasmania

APPENDIX H

Specifications - RMS Instruments Automatic Aeromagnetic Digital Compensator

INPUTS

one to four high sensitivity magnetometers of optical absorption

INPUT FREQUENCY RANGE

70 KHz - 350 KHz - Cs sensor 140 KHz - 700 KHz - K sensor 560 KHz - 2800 Khz - He sensor

850 Hz - 4 260 Hz - Overhauser

MAGNETIC FIELD RANGE

20000 - 100000 nT (gamma)

RESOLUTION

1 pT (picotesla)

COMPENSATION PROCEDURE:

improvement ratio 10-20 typical for total field

improvement ratio 20-100 typical for gradient

ACCURACY OF

COMPENSATION

0.035 nT (gamma) standard deviation for the entire aircraft flight

envelope in the bandwidth 0-1 Hz typical.

DATA OUTPUT RATE

10 Hz

SYSTEM FREQUENCY

 $0 - 0.9 \, \text{Hz}$

RESPONSE

INTERNAL SYSTEM NOISE

less than 2 pT (standard deviation in the bandwidth 0-1 Hz)

DURATION OF CALIBRATION:

FLIGHT MANOEUVRES

5-8 minutes typical

MICROCOMPUTER

SBC-11/21 Plus (DEC) Front End LSI-11/73 (DEC) Main CPU

KEYBOARD

limited alphanumeric

DISPLAY

green fluorescent, 80 character self scan panel

OUTPUTS

serial data communication port: RS232C - max. rate 19.2 K Baud

parallel output port: 16 bit with full handshaking (DRV11-J)

(optional)

POWER

: 28 ± 4 VDC, 5A, 150W (for single magnetometer) 7A, 196W

(for gradiometer system)

ENVIRONMENTAL

operating temperature: 0 to 50°C

storage temperature: -20 to 55°C

relative humidity: 0-99%, non-condensing

altitude: 0 to 6000 m (0 to 20000 ft)

PHYSICAL DATA

console dimension: 483 x 178 x 440 mm

console weight: 12.5 kg

power supply dimensions: 225 x 180 x 220 mm

power supply weight: 5.5 kg

APPENDIX I Arthur - Pieman Area North West Tasmania

APPENDIX I

Specifications - Exploranium GR820 Spectrometer System

Detector Controller

- Maximum number of crystals 16. Each crystal has individual pole-zero cancellation, semi gaussian shaping and advanced base line restoration circuitry.
- Continuous, individual-crystal spectrum analysis ensures that optimum system stabilisation is achieved. Resolution is calculated by a sophisticated gaussian curve fitting algorithm to perform an accurate centroid analysis of the selected stabilisation peak.
- High energy cosmic pulses are accumulated in a separate channel.
- Accurate pile-up rejection for simultaneous pulses allows qualitative gamma-ray spectrum analysis
 almost independent of the system count rate. Special circuitry analyses for pulse pile-up and
 permits only detector signals from single events to be analysed. Simultaneous events in adjacent
 crystals are added to reduce the Compton effect.
- Residual pulse pile-up at 100000 counts/sec are less than 2%

Analog to digital converter (ADC)

- 50 MHz Wilkinson ramp ADC.
- Linearity integral less than 0.2%; -differential less than 1%
- Average system dead-time is less than 5 microsec/pulse.
- Live-time channel records the actual system live-time. This data is output with the digital data which allows post correction for system dead-time to an accuracy of 0.1%.
- Number of channels selection of 256 channels or 512 channel operation.
- Maximum number of counts/channel 65535 (16 bits).
- The lower threshold manually selectable from channel 2 to channel 50 (20-500 keV).
- The upper threshold is set to 3 MeV. All pulses above 3 MeV are accumulated in the cosmic channel as a direct measure of cosmic ray activity.
- ADC offset set from the keyboard.
- The maximum input count rate is 100000 counts/second.

System outputs

- Visual display the front panel display is a 640 x 200 electroluminescent (EL) high contrast graphics display which allows full spectrum display, system set-up and various parameter monitoring functions. In the spectrum display mode, the region of interest and cursor may be viewed by channel number or directly in keV.
- The internal channel number to energy level (keV) conversion table compensates for non-linearity of the detector's light output.
- The front panel has a 21 button keyboard for easy operator control.
- The system's operation is fully menu driven.

Digital outputs

- RS-232 port (1200 to 19200 baud).
- IEEE-488 bus output talk listen/talk only.
- Geometrics GR-800 output format.
- Some system functions can be controlled remotely by an external computer via the RS-232 and the IEEE-488 digital ports.

Analog output

4 channels of roi data can be selected for output on the analog port. The outputs have 10 bit resolution (0-10V). Scaling can be set from the keyboard (100-50 K counts/sec FSD) and output data may be raw or stripped using internally stored calibration constants. Analog output wraps at fsd limits and is dead-time corrected.

Miscellaneous

- Regions of interest (ROI) 8 ROIs can be selected. The upper and lower thresholds can be individually set over the entire spectrum range.
- The first 4 ROIs are available for digital and analog output. The second 4 ROIs are available only for digital output on the RS-232 or the IEEE-488 ports.
- System resolution. Detector resolution is automatically computed for each (and summed crystals) during peak analysis and is displayed for operator monitoring when required. The summed down resolution is also output on the data stream.
 - System test. At power on, a full system test of all internal pcb handshaking is performed. Included in the testing is the lithium back-up battery, the system ram memory, display handshaking, the systems configuration (options installed), the selected detectors (checked via ADC analysis) and peripheral handshaking response.
- Configuration menus. The configuration menus allow the selection of the number of detectors in
 use, confidence levels for gain analysis, maximum crystal resolution levels for each detector (with
 operator warning if levels exceeded), output configurations for analog and digital data and various
 special display/monitoring functions.
- Maintenance. A set of special menus allows the user to test and calibrate many systems functions including system test, ADC offset, low level discriminator etc.
- Power: 28V 1.25amps.

Detectors

The crystals are housed in a specially designed hi-impact polystyrene cases using low background materials for minimum signal attenuation. Full thermal and internal shock protection allows the units to be directly mounted to the floor. A very low noise, high voltage power supply is housed in each pack so high voltage is not present in the connecting cables. A unique preamplifier with special processing for signal optimisation is used. The GPX-1024 has 4 crystals with a total volume of 16.78 litres.

- Outputs. Individual BNC connectors output each crystal's signal separately.
- Size: GPX-1024: 73 x 51 x 30 cm
- Weight: GPX-1024: 84 kg
- Power: 28V @ 0.5 A/crystal pack

• Temperature limitations

- Closed pack: storage -40°C to +60°C, operation -40°C to 60°C
- Open pack: not recommended
- Temperature gradient:

Closed pack: -40°C to +50°C (instantaneous)

Open pack: a change of 1°C/hour.

APPENDIX J Arthur - Pieman Area North West Tasmania

APPENDIX J

Specifications - Novatel 951R Global Positioning System Card

FREQUENCY

L1, 1575.42 MHz

CODE TRACKED

C/A Code (SPS)

CHANNELS

12 Discrete Channels

TIME TO FIRST FIX

<70 seconds typical (cold start: no initial time,

almanac, or position required)

RE-ACQUISITION

3 seconds typical

COMPUTED DATA UPDATE

10 solutions per second

RATE

SINGLE CHANNEL PHASE

ACCURACY

3 mm RMS, C/No> 44 dB Hz

loop BW=15Hz

DIFFERENTIAL CHANNEL

PHASE MEASUREMENT

ACCURACY

0.75 mm RMS, 1 second smoothed, no multipath,

C/No> 44d BHz

TIME ACCURACY (RELATIVE):

50 nanoseconds (SA off)

250 nanoseconds (SA on)

HEIGHT LIMIT

60000 ft maximum

VELOCITY LIMIT

Up to 575 ms⁻¹ maximum

OPERATING TEMPERATURE

0° to +70°C

SIZE

216 mm x 107 mm x 19 mm

WEIGHT

220 g

MOUNTING

installed inside an IBM-PC Compatible

APPENDIX K

Arthur - Pieman Area

North West Tasmania

APPENDIX K

Specifications - Bendix King KRA-10A Radar Altimeter

KRA 10A Receiver/Transmitter

ALTITUDE OUTPUT RANGE

20 ft. to 2500 ft. max.

AGL - Maximum

Altitude is dependant on ground reflectivity

ACCURACY

± 5 ft. 50 ft. to 100 ft.

(with or without KI 250)

 \pm 5% 100 ft. to 500 ft.

 \pm 7% 500 ft. to 2000 ft.

POWER REQUIREMENTS

27.5 VDC ± 20% @ 200 ma Max. Total for system

ALTITUDE

45000 ft. (13716 m)

TEMPERATURE

- 54°C to 71°C

COOLING

Convection

SIZE

 $7.9 \times 8.9 \times 20.3$ cm

WEIGHT

0.9 kg

MOUNTING

Any position

AUX. ANALOG OUTPUT

+ 4 my/ft.

KI250 Indicator

ALTITUDE RANGE

20 to 2500 ft. AGL

DECISION HEIGHT RANGE

(pilot adjustable)

20 to 2500 ft. AGL

DH LAMP

: Lights when descending thru DH

DH AUDIO

2 sec. 1 KHz tone when descending thru DH

ALTITUDE

15000 ft. (4,572 m)

TEMPERATURE

- 15°C to 71°C

COOLING

Convection

SIZE

8.28 x 10.0 x 8.28 cm

WEIGHT

: 0.4 kg

KA 131 Antenna

BEAMWIDTH

E-Plane

H-plane

: 40 ± 5° : 40 ± 5°

MOUNTING SURFACE ANGLE FROM HORIZON

KA 131-00 (parallel) : $\pm 6^{\circ}$ KA 131-01 (skewed) : 6° to 20°

APPENDIX L Arthur - Pieman Area North West Tasmania

APPENDIX L

Specifications - Vaisala HMD50Y Temperature and Humidity Sensor

Relative Humidity

OPERATING RANGE

0-100% RH

SENSOR

Intercap Humidity Sensor, Part No. 15778

Temperature

OPERATING RANGE

-10°C to 60°C

TOTAL ACCURACY AT 25°C :

 ± 0.3 °C

SENSOR

PR 1000 DIN 43760B

General

OUTPUT SIGNAL

Equals 0 to 100% RH and -40°C to 60°C

0 to 10V

Load Resistance > 10k OHM

POWER SUPPLY

15 to 35 VDC

CURRENT CONSUMPTION

6mA typical

HOUSING CLASSIFICATION

IP 65

APPENDIX M

Arthur - Pieman Area

North West Tasmania

APPENDIX M

Specifications - Intellisensor Air-DB Digital Barometer

PRESSURE RESOLUTION

0.01 HPa

ALTITUDE RESOLUTION

0.1 m

MAX. OPERATING PRESSURE :

1300 HPa

OPERATING MODULES

Barometer Altimeter Altimeter Setting, Test

SELECTABLE DATA UNITS

Pressure - mb, in Hg, mm Hg, psia

Altitude - feet, metres Altimeter Setting - in Hg

SAMPLING RATE (MAX)

10/second

SELECTABLE AVERAGING

1, 10, 100, 1000 samples/average

SELECTABLE INTERFACES

RS-232C or LSTTL Serial (110, 300, 1200, 9600 baud)
Parallel (8-bit with handshaking)

DATA FORMAT

Serial ASCII, Parallel ASCII or binary

POWER REQUIREMENTS

RS-232C +11 to +16 and -11 to -16 VDC

14.5 mA (oper), 8.5 mA (stdby)

LSTTL Serial or parallel +8 to +16 VDC

6.3 mA (oper), 10 uA (stdby)

SIZE

Length - 8.9 cm

Diameter - 8.9 cm

WEIGHT

 $0.58 \, \mathrm{kg}$